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Research Article

False Alarm Rate Estimation for Information-Theoretic-Based Source Enumeration Methods

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The Tracy-Widom distribution is used to determine the false alarm rate of information theoretic methods that statistically estimate the number of sources in a multichannel receiver input. The Tracy-Widom distribution is the limiting distribution for the largest eigenvalue of a covariance matrix having a central white Wishart distribution. Such covariance matrices are produced by the output of multi-channel receivers whose signals can be characterized as zero-mean Gaussian processes. The Tracy-Widom distribution is used to estimate the false alarm rate of the Akaike Information Criterion and Minimum Description Length methods when no external sources are present. The Tracy-Widom distribution along with the eigenvalue inclusion principle is used to obtain an upper bound on the false alarm rate of the Akaike Information Criterion and Minimum Description Length when one external source is present. Monte-Carlo simulations were performed to demonstrate the effectiveness of both methods for cases where both the array and data sample sizes are small.

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1. Introduction

The performance of information-theoretic-based methods for model selection is difficult to analyze for small sample sizes. Such a performance analysis is necessary because these methods are based on asymptotic approximations which are invalid for small samples [1]. In signal processing applications, scenarios occur when small sample sizes may be necessary or desirable to use (e.g., smart antennas signal processing for moving platforms). In this paper, we introduce a new method to evaluate the small sample performance of two information-theoretic-based methods commonly used in signal processing for a specific type of model selection: estimating the number of directional sources from the output signal of an array.

In this paper, we will analyze the small sample performance of the Akaike Information Criterion (AIC) [2, 3] and the Minimum Description Length (MDL) [4, 5], two commonly used information-theoretic approaches for source enumeration [6]. Because the focus of this paper is the small sample performance of information-theoretic methods for source enumeration, rather than determining which method for source enumeration is best, we will not

consider other methods for source enumeration that exist [7, 8] in our analysis. Early analyses show that for large sample sizes, the MDL is a consistent estimator for the number of sources, while the AIC tends to overestimate the number of samples [9]. Subsequent performance analyses for arbitrary sample sizes, however, have either relied on the use of large array sizes [10], large sample sizes [10, 11], computationally expensive Monte-Carlo simulations [12], or involved the use of quantities which are difficult to evaluate numerically [13]. In this paper, we introduce a method to estimate the false-alarm rate (FAR) for the AIC and MDL. The contribution of our approach is that it can be used for arbitrary array and data sizes and is simple and computationally inexpensive to use, thereby making it practical for use in real-time applications.

Our approach is based on a recent development in random matrix theory known as the Tracy-Widom (TW) Law. The TW law states that the largest eigenvalue of a covariance matrix having a central white Wishart distribution converges to a limiting distribution known as the TW distribution [14]. Such covariance matrices occur in array signal processing applications where the output signal of a multi-channel receiver can be modeled as the sum of i.i.d.

zero-mean Gaussian processes. It will be shown that the utility of the TW distribution derives from two important properties it possesses. First, the TW distribution transforms the largest eigenvalue into a standardized random variable whose distribution is independent of the array and sample size [15, 16]. Given K array elements, from which N samples are collected, the largest eigenvalue of the sample covariance matrix, λ_1 , can be used to construct the standardized test statistic $z = (\lambda_1 - \mu_{K,N})/\sigma_{K,N}$. Although $\mu_{K,N}$ and $\sigma_{K,N}$ are functions of N and K, the TW distribution of the standardized random variable, z, is the same for all values of K and N. Thus, regardless of the array size or the number of samples, the P-value of z can be determined from a single table for the values of the TW cumulative distribution function (CDF) just like the standard normal distribution. Second, the TW distribution is applicable over virtually any size of array and input sample size (despite the fact that the TW was originally derived as the distribution for λ_1 in the limit of both K and N going to infinity) [16]. This marks an important distinction between the TW distribution and the distributions for the largest eigenvalue derived from previous studies. The exact distribution of the largest sample eigenvalue has been derived for arbitrary array sizes but is only valid in the limit of large sample sizes [17]. A later attempt to derive an approximation to the exact distribution valid for finite sample sizes required the use of expressions that are difficult and computationally expensive to evaluate numerically [18]. Although an exact distribution for the largest eigenvalue for any sample and array size exists, it too is difficult to numerically evaluate efficiently [19]. In the case of [18, 19], the evaluation of their distributions requires computing the ratio of an incomplete Gamma function and a complete Gamma function, whose arguments are both on the order of the sample size. Attempts to obtain reliable approximations to these ratios are cumbersome, complicated, and require the use of look-up tables [18]. On the other hand, it will be demonstrated that the TW distribution is simple, straightforward to use, and agrees well with the right-hand tail of the distribution for the largest eigenvalue of the sample covariance matrix for array sizes from K = 3 to K = 9 and with sample sizes that range from the minimum number of samples required to estimate the covariance matrix well (which is max(3*K, 2*K - 3) [20]) up to 20^*K .

The outline of the paper will be as follows. In Section 2, we present the TW distribution and compare its distributional behavior to that of the largest eigenvalue from sample covariance matrices for small array and data sample sizes. In Section 3, the AIC and MDL will be derived under the condition that the variance in the input noise is known. In Section 4, the TW law is used to estimate the FAR for the AIC and MDL when there is no external source and when there is only one external source present, respectively. In Section 5, we summarize the results of the paper.

2. The Tracy-Widom Law

The TW law states that a standardized form of the largest eigenvalue for a covariance matrix having a central

white Wishart distribution approaches a unique limiting distribution. Consider N random vectors with K components, \mathbf{X}_n , with multivariate normal distribution \mathbf{X}_n i.i.d. $\mathcal{N}_{\beta}(\mathbf{0}, \sigma^2 I_K)$ for $n=1,\ldots,N$, where σ^2 denotes the noise variance and I_K is the K by K identity matrix. Following the notation of Dyson [21], $\beta=1$ and $\beta=2$ indicate the real and complex normal distributions, respectively. The sample covariance matrix, \hat{R} , is constructed from the data samples (from which their mean has been subtracted) using $\hat{R}=(1/N)(\sum_{n=1}^{N}\mathbf{X}_n\mathbf{X}_n^H)$, where superscript H denotes conjugate transpose.

The eigenvalues of \hat{R} , called the sample eigenvalues, are determined and ranked according to their magnitude such that $\hat{\lambda}_1 \geq \cdots \geq \hat{\lambda}_K$. Under these conditions, the TW law states that:

$$z \stackrel{\text{def}}{=} \frac{\hat{\lambda}_1 - \mu_{K,N}}{\sigma_{K,N}} \stackrel{\mathcal{D}}{\longrightarrow} F_{\beta} \quad \text{as } \frac{K}{N} \longrightarrow c \ni 0 < c < 1, \quad (1)$$

where

$$\mu_{K,N} = \frac{\left(\sqrt{K} + \sqrt{N - 2 + \beta}\right)^2}{N},$$

$$\sigma_{K,N} = \frac{\left(\sqrt{K} + \sqrt{N - 2 + \beta}\right)}{N} \left[\frac{1}{\sqrt{K}} + \frac{1}{\sqrt{N - 2 + \beta}}\right]^{1/3},$$
(2)

and F_{β} is the TW CDF, shown in Figure 1. F_{β} must be computed numerically, and its values have been tabulated to four significant digits for z values in increments of 0.01 [22]. A complete published table for both F_1 and F_2 is available [23] and a downloadable copy of these files is also available on the MatLab Central website (see http://www.mathworks.com/matlabcentral/fileexchange/24590. In this sense, the TW distribution works the same way as the standard normal distribution, which also must be numerically computed and requires a single look-up table for its use. Since only complex covariance matrices will be considered in our analysis, F_2 will be used exclusively from this point on.

Figure 2 plots the difference between F_2 and the empirical cumulative distribution functions (ECDF) with respect to z for K = 2, 3, 5, 7, and 9. The ECDF for each K was generated from one million Monte-Carlo simulations, using N = 3K random samples on each trial. Based on this figure, we observe the following four important relationships between the TW distribution and the distribution for the largest sample noise eigenvalue.

Observation 1. The TW distribution provides a good approximation to the right-hand tails of the largest eigenvalue's distribution function even when *K* and *N* are small.

Figure 2 shows that the agreement between the ECDFs and the TW CDF is good in the right-hand tail of the distributions. Around z = -1.0 (which according to Figure 1 is slightly above the 80% level of the CDF), *all* the ECDFs cross F_2 . For z > -1, the difference between the ECDFs and

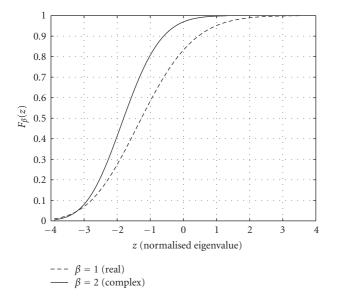


FIGURE 1: The cumulative distribution functions of the TW distributions for real and complex white Wishart covariance matrices as a function of the standardized random variable *z* given in (1).

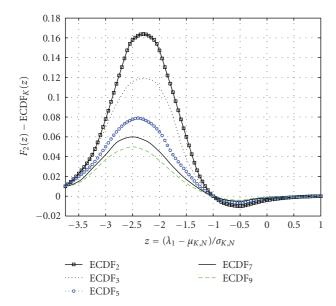


FIGURE 2: The difference in F_2 , the TW CDF, and the empirical CDFs of z for various values of K using N = 3K. The two classes of distributions are in good agreement past z = -1, the 80th percentile level for F_2 .

the TW distribution is less than 1% for all values of K. A more quantitative look at the agreement between the right-hand tail of the TW distribution with that of the ECDFs is shown in Table 1. The CDF for the standardized form of the largest sample eigenvalue was estimated at three z values corresponding to the CDF values for the TW distribution at 90%, 95%, and 99%. The ECDF values were determined for 5 different array sizes (K = 2, 3, 5, 7, and 9) with N = 3K. The last column gives an estimate for twice the standard error (SE) of the ECDF values based on that obtained from

Table 1: ECDF values for the 90%, 95%, and 99 % F_2 CDF Values.

E. CDE (in %)	ECDF Values (%) for $N/K = 3$ K = 2 $K = 3$ $K = 5$ $K = 7$ $K = 9$					2*SE (in %)
12 CDT (III 70)	K = 2	K = 3	K = 5	K = 7	K = 9	2 3E (III 70)
90	90.97	90.74	90.54	90.41	90.035	± 0.06
95	95.85	95.65	95.46	95.53	95.25	± 0.04
99	99.23	99.18	99.11	99.07	99.05	± 0.02

binomial sampling, SE = $\sqrt{p(1-p)/N_{\text{SIMS}}}$, where p is the true CDF value, and the number of simulations $N_{\text{SIMS}} = 10^6$. Despite the agreement between the values of the TW CDF and the ECDFs, the difference between them typically exceeds 2 SE units, and is therefore statistically significant.

Observation 2. The distribution for the standardized largest sample noise eigenvalue is stochastically less than the TW distribution.

Figure 2 shows that for z > -1, the sign of the difference in the CDFs is always negative. An important consequence of this observation is that $P(z \ge Z \mid z = (\lambda_1 - \mu_{K,N})/\sigma_{K,N}) \le P(z \ge Zz \sim F_2)$ for all Z > -1. Thus, we see that if the TW distribution is used to approximate the true distribution for the largest sample noise eigenvalue, it will always overestimate the probabilities of events in the right-hand tail of the distribution.

Observation 3. As K increases, while K/N is held constant, the normalized largest sample noise eigenvalue's distribution functions approach the TW distribution.

This observation is a direct consequence of (1). Figure 2 illustrates this fact since the ratio of N/K is fixed at 3 for all of the ECDF curves. Figure 2, along with Table 1, shows that not only does the convergence occur as K increases, but that it is relatively rapid.

Observation 4. The agreement between the TW and standardized largest noise eigenvalue's distribution generally improves as the *P*-value decreases (for *P*-values < 10%).

The agreement between the TW CDF and the ECDFs shows a general uniform improvement for z > -0.5, which is a fraction of a percentile past the 90% CDF value for F_2 .

The relationship between the TW distribution and the limiting distribution of the standardized sample eigenvalue in the limit as N goes to infinity (while K is held fixed) is difficult to determine. Technically, they are not required to converge, since the hypothesis required for the TW law to hold, that the ratio of K/N to converge to a positive number less than one, is not satisfied. It is known that as K is held fixed and N increases, the maximum eigenvalue converges to unity (almost surely), so that the distribution of the maximum eigenvalue becomes degenerate in the limit of $N \rightarrow \infty$ [24]. This fact, however, is of no apparent use in trying to understand the limiting distribution of the standardized sample eigenvalue, because although the support for the distribution of the quantity $\hat{\lambda}_1 - \mu_{K,N}$ clearly

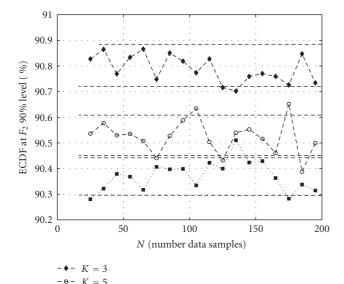


FIGURE 3: The ECDF values at the 90% level for F_2 are computed as a function of the number of data samples for three different array sizes. The dashed lines give a bounds of $\pm 1\sigma$ about the mean.

goes to zero as $N \to \infty$, so does the scale factor $\sigma_{K,N}$. Although this problem is not of central importance in our analysis (which focuses on small sample sizes), simulations indicate that the difference in the distributions appears to stay about the same for each K up to at least N < 20K. Figure 3 plots the ECDF values for the 90% level for the TW distribution as a function of N for K = 3,5, and 9. The values at each data point shown are obtained using 100,000 Monte-Carlo simulations. The mean of the ECDF values is computed and a one-standard error range about the mean (dashed parallel lines) is plotted along with the ECDFs. It is seen that the ECDF values mostly stay within the one-standard error range.

3. Information-Theoretic Criterion

3.1. Preliminaries. The AIC and MDL are used in likelihood estimation problems when the number of parameters in a statistical model is not fixed. Although they are derived in different ways, both provide a measure of how well members from a family of distributions agree with some true distribution [3, 5]. In both cases, the chosen model is that which minimizes an information theoretic criterion, which for our purpose can be expressed in the generic form:

$$IC = -\ln[f(\mathbf{X} \mid \hat{\boldsymbol{\theta}})] + \gamma_{IC}\eta, \tag{3}$$

where f is the probability density function of the model distribution, \mathbf{X} denotes a given random sample, $\hat{\boldsymbol{\theta}}$ is the vector of the maximum likelihood estimates (MLEs) for the model parameters, η is the number of degrees of freedom in the model, and $\gamma_{\rm IC}$ is a parameter dependent on which IC method is used. For the AIC, $\gamma_{\rm IC}=1$, while $\gamma_{\rm IC}=\ln(N)/2$ for the MDL.

The AIC and MDL can be used to estimate the number of sources in a multichannel signal [6]. The exact implementation of the method depends on the signal structure of the sources, channel noise, and array configuration considered [25]. For simplicity, we will consider a uniform linear array of K ideal isotropic elements. We adopt the statistical signal model used in [6]:

$$\mathbf{X}(n) = \sum_{m=1}^{M} \mathbf{A}(\theta_m) S_m(n) + \varepsilon_n \quad \text{for } n = 1, \dots, N.$$
 (4)

In this model, there are a total of M sources (where $M \leq K$). The nth sample of the signal from the mth source, $S_m(n)$, is a stationary, complex random process having the distribution $\mathcal{N}_2(0, \sigma_m^2)$. In our analysis, the signals used will have the form $S_m(n) = \exp\{j[\omega t_n + \varphi_m(n)]\}$, where the phase at each time sample is a random variable such that $\varphi_m(n) \stackrel{\text{i.d.d.}}{\sim} \text{Unif}(\mathbf{0}, 2\pi)$. The $K \times 1$ complex vector, $\mathbf{A}(\theta_m)$, is the array steering vector for the mth source whose angle of arrival is θ_m . We assume that the collection of vectors, $\{\mathbf{A}(\theta_m)\}_{m=1}^M$, are linearly independent. The random channel noise at the nth sample is modeled as the complex random vector $\varepsilon_n \stackrel{\text{i.d.d.}}{\sim} \mathcal{N}_2(\mathbf{0}, \sigma^2 I_K)$. We shall assume σ^2 is known (since it can be estimated from an analysis of the receiver's signal in the absence of any sources) and for the remainder of the analysis, we will set $\sigma^2 = 1$.

3.2. AIC and MDL Derivation (Known Noise Variance). This subsection derives the explicit form of the AIC and MDL IC under the assumption that the noise variance is known.

The MLE for the model parameters given *M* sources must first be determined. Our starting point is the general form for the log-likelihood function of the signal model given in the last section [9]:

$$L|_{M} = -N \operatorname{Trace}\left[(R|_{M})^{-1} \widehat{R} \right] - N \ln[\operatorname{Det}(R|_{M})] - NK \ln \pi,$$
(5)

where $R|_M$ is the population covariance matrix for the M source model, and \hat{R} is the sample covariance matrix. The quantities associated with sample covariance matrix, maximum likelihood estimates, and population covariance matrix will be denoted with hats, tildes, and no markings, respectively.

The eigenstructure of the population covariance matrix for a collection of M narrowband, uncorrelated sources can be expressed as the direct sum of two subspaces, the signal subspace and noise subspace. The signal subspace has dimension M. It has M distinct population eigenvalues greater than unity, which shall be ordered such that $\lambda_1 > \cdots > \lambda_M$. Its orthogonal complement, the noise subspace, has dimension K-M, and its population eigenvalues are all unity. Hence, the inverse of the population covariance matrix under this model, $(R|_M)^{-1}$, can be expressed in spectral form as

$$(R|_{M})^{-1} = \sum_{m=1}^{M} \frac{1}{\lambda_{m}} \mathbf{u}_{m} \mathbf{u}_{m}^{H} + \sum_{k=M+1}^{K} \mathbf{u}_{k} \mathbf{u}_{k}^{H}.$$
 (6)

Substituting (6) into (5), using the cyclic permutation property of the trace operator, and dropping the constant term, we obtain

$$L\mid_{M} = -N \left\{ \sum_{m=1}^{M} \frac{1}{\lambda_{m}} \mathbf{u}_{m}^{H} \hat{R} \mathbf{u}_{m} + \sum_{k=M+1}^{K} \mathbf{u}_{k}^{H} \hat{R} \mathbf{u}_{k} \right\} - N \sum_{m=1}^{M} \ln(\lambda_{m}).$$

$$(7)$$

The MLE estimates the eigenvalues and eigenvectors of the signal subspace. They are found by maximizing the likelihood function subject to the constraint that the signal eigenvalues are greater than or equal to one and the signal eigenvectors be orthonormal. The details of the solution to this problem can be found elsewhere [26]. The MLEs for the eigenvectors are found to be the eigenvectors of \hat{R} , and the MLEs for the eigenvalues are $\tilde{\lambda}_m = \text{Max}\left[\hat{\lambda}_m, 1\right]$ for $m = 1, \ldots, M$. This solution produces the maximum log-likelihood function:

$$\widetilde{L}|_{M} = -N \left\{ \sum_{m=1}^{M} \left[\left(\frac{\widehat{\lambda}_{m}}{\widetilde{\lambda}_{m}} \right) + \ln(\widetilde{\lambda}_{m}) - \widehat{\lambda}_{m} \right] + \sum_{k=1}^{K} \widehat{\lambda}_{k} \right\}.$$
(8)

The last term needed to determine the form of the AIC is the number of free parameters. Since our model consists of M eigenvalues (which are real scalars) and M eigenvectors (which have K complex components), it follows that the total number of parameters in our model is M + 2KM. The 2KM components of the signal eigenvectors, however, are not all independent of each other. In fact, there are a total of M^2 constraint equations that they must satisfy: M of these equations come from the constraint that the eigenvectors have unit length, while the M(M-1) remaining equations come from the orthogonality constraint. The number of parameters required to characterize M orthonormal vectors embedded in \mathbb{C}^K is a known result in algebraic geometry. The parameter space of these vectors forms a manifold, known as the complex Stiefel manifold, which has been proven to have dimension M(2K-M) [27]. This result implies that the total number of free parameters in our model is

$$\eta(M) = M + 2KM - M^2 = M[(2K+1) - M]. \tag{9}$$

This result corrects a previous error in the literature, in which it is stated without proof that the total number of free parameters (for the eigenvalues and eigenvectors) is M(2K - M) [9].

It follows from (3), (8), and (9), that the IC for our model can be expressed in the following form:

$$IC = N \left\{ \sum_{m=1}^{M} \left[\left(\frac{\hat{\lambda}_{m}}{\tilde{\lambda}_{m}} \right) + \ln \left(\tilde{\lambda}_{m} \right) - \hat{\lambda}_{m} \right] + \sum_{k=1}^{K} \hat{\lambda}_{k} \right\}$$

$$- \gamma_{IC} \left[M^{2} - 2M \left(K + \frac{1}{2} \right) \right].$$
(10)

It is convenient to represent the expression on the right hand side of (10) as a function of *M*:

$$\Gamma(M) \stackrel{\text{def}}{=} \sum_{m=1}^{M} \left[\left(\frac{\widehat{\lambda}_{m}}{\widetilde{\lambda}_{m}} \right) + \ln\left(\widetilde{\lambda}_{m} \right) - \widehat{\lambda}_{m} \right] + \sum_{k=1}^{K} \widehat{\lambda}_{k}$$

$$- \frac{\gamma_{\text{IC}}}{N} \left[\left(K + \frac{1}{2} \right) - M \right]^{2}.$$
(11)

A second quantity which will be useful in the next section is the difference between $\Gamma(M+1)$ and $\Gamma(M)$:

$$\Delta\Gamma(M) \stackrel{\text{def}}{=} \Gamma(M+1) - \Gamma(M) = \left[\left(\frac{\widehat{\lambda}_{M+1}}{\widetilde{\lambda}_{M+1}} \right) + \ln(\widetilde{\lambda}_{M+1}) \right] - \widehat{\lambda}_{M+1} + \gamma_{\text{IC}} \frac{2(K-M)}{N}.$$
(12)

4. The IC False Alarm Rate

4.1. False Alarm Rate Approximation. The FAR is a measure by which the number of sources is overestimated. It is defined as the probability that the number of estimated sources is greater than the true number of sources. In general, the FAR will be a function of the number of sources present, and can therefore be computed as the sum of the conditional probabilities of the disjoint events:

$$P_{\text{FA}}(M) = \sum_{\widehat{M}=M+1}^{K} P(\widehat{M} \mid M), \tag{13}$$

where $P(\widehat{M} \mid M)$ denotes the probability that the IC estimates \widehat{M} sources are present, given that M sources are present.

It is reasonable to assume that the estimated number of sources has some distribution about M, and that the leading contribution to the FAR for M sources should be at $\widehat{M} = M + 1$. In fact, it has been found that when K > 2 and $M = \{0, 1\}$, to a good approximation [28]:

$$P_{\text{FA}}(M) \approx P(\widehat{M} = M + 1 \mid M),$$
 (14)

thereby reducing the determination of the FAR to estimating the probability of a single event.

As a final observation, we note that the probability of the event on the RHS of (14) is less than the true FAR. This might lead one to think that the probabilities for the FAR we are obtaining will be lower bounds on the true FARs. Even though the probability on the RHS of (14) is a lower bound on the true FAR, the probability we will be computing will not be $P(\widehat{M} = M + 1 \mid M)$ but rather an approximation to it using the TW law. Because the TW distribution is stochastically greater than the distribution using the standardized largest eigenvalue (which is how $P(\widehat{M} = M + 1 \mid M)$ is computed), the FAR that is computed will be greater than $P(\widehat{M} = M + 1 \mid M)$. It turns out that the difference between $P_{FA}(M)$ and $P(\widehat{M} = M + 1 \mid M)$ is much smaller than the difference between $P(\widehat{M} = M + 1 \mid M)$ and its approximation using the TW law. Hence, the final FAR computed will actually be an upper bound on the true FAR.

4.2. Estimation of the IC FAR for M=0. Using the approximation from the previous section for the case when M=0 makes it necessary to only consider the contribution of the event $\widehat{M}=1$ to the FAR. Since the estimate for the number of sources minimizes the IC, it follows that the approximation for the FAR can be rewritten as

$$P_{\text{FA}}(0) \approx P(\Gamma(1) < \Gamma(0) \mid 0). \tag{15}$$

The event on the right hand side of (15) is $\Delta\Gamma(0) < 0$, which using (13) is given by

$$P_{\text{FA}}(0) \approx P\left(\frac{\hat{\lambda}_1}{\tilde{\lambda}_1} + \ln(\tilde{\lambda}_1) - \hat{\lambda}_1 + \frac{2K\gamma_{\text{IC}}}{N} < 0\right),$$
 (16)

where $\widetilde{\lambda}_1 = \operatorname{Max}[\widehat{\lambda}_1, 1]$. The MLE for the largest eigenvalue has two possible cases: $\widetilde{\lambda}_1 \leq 1$, and $\widetilde{\lambda}_1 > 1$. For $\widetilde{\lambda}_1 \leq 1$, (16) reduces to $P_{\text{FA}}(0) \approx P(2\gamma_{\text{IC}}K/N < 0)$, which is not possible. This result is not surprising, since the decision that $\widehat{M} = 1$ when the largest eigenvalue was less than one would be equivalent to deciding a source was present when its signal eigenvalue was less than one. Hence, when M = 0, the only case that needs to be considered is $\widetilde{\lambda}_1 > 1$, for which the FAR reduces to

$$P_{\text{FA}}(0) \approx P\left(1 + \ln\left(\hat{\lambda}_1\right) - \hat{\lambda}_1 + \frac{2K\gamma_{\text{IC}}}{N} < 0\right).$$
 (17)

The function $g_1(\hat{\lambda}_1) = 1 + \ln(\hat{\lambda}_1) - \hat{\lambda}_1 + 2K\gamma_{\rm IC}/N$ is positive at $\hat{\lambda}_1 = 1$ and monotonically decreases for $\hat{\lambda}_1 > 1$. Thus, g_1 has exactly one zero for $\hat{\lambda}_1 > 1$, which can easily be found numerically. Denoting the zero of g_1 by Λ_1 , (17) can be written as

$$P_{\text{FA}}(0) \approx P(\hat{\lambda}_1 > \Lambda_1).$$
 (18)

The probability on the right-hand side of (18) can be evaluated by rewriting it as

$$P_{\text{FA}}(0) \approx P\left(\frac{\hat{\lambda}_1 - \mu_{K,N}}{\sigma_{K,N}} > \frac{\Lambda_1 - \mu_{K,N}}{\sigma_{K,N}}\right).$$
 (19)

Approximation of the test statistic's distribution by the TW distribution is reasonable if the FAR is less than 20%. Thus, assuming that the FAR is less than 20%, and using the TW distribution as an approximation to the true test statistic give the approximation to the FAR when M=0 as

$$P_{\rm FA}(0) \approx 1 - F_2 \left(\frac{\Lambda_{\rm Crit} - \mu_{K,N}}{\sigma_{K,N}} \right).$$
 (20)

The accuracy of this method is tested using simulation. A comparison of the approximate FARs obtained from (20) with the FARs obtained from simulation for the AIC and MDL are shown in Figures 4(a) and 4(b), respectively. The FARs for two different array sizes as a function of N are analyzed in both figures. Smaller values of K are used for the MDL due to the fact that the FARs for K > 6 are less than 1/100 of 1%, which is too small to be computed reliably with

Table 2: Estimated Error in TW Approximated AIC FARs for M=0.

	Mean Absolute Difference in FARs	Mean Relative Difference in FARs		
K				
3	0.36%	18%		
5	0.23%	14%		
7	0.16%	11.5%		
9	0.13%	10.3%		

the TW distribution used in our analysis. A smaller range for N is also used for the MDL, as it is found to converge to zero very rapidly. For each value of K and N, 10^6 Monte-Carlo simulations were run using complex white noise. The covariance matrix and its eigenvalues are computed and substituted into (10) to determine the number of sources that minimize the IC. The percentage of these runs for which $\widehat{M} > 0$ is the estimated FAR for M = 0.

As Figures 4(a) and 4(b) show, the theoretically predicted FAR using the TW law provides a good estimate of the computed FAR when M = 0 for both the AIC and MDL. Both figures suggest that the TW FAR estimate is an upper bound on the true FAR. This finding is a direct consequence of Observation 2. As *K* increases, the approximation to the FAR improves, which is a direct consequence of Observation 3. The agreement between the FARs obtained from theory and simulation is better for the MDL than for the AIC. This is due to the fact that the FARs are smaller for the MDL than the AIC, hence by Observation 4, this result is also expected. To obtain a more quantitative understanding of the discrepancy between the theory and simulation for AIC, we computed the mean absolute and relative difference between the FAR obtained from simulation and theory. Table 2 compares these differences between the theoretical and simulated FARs for K = 3,5,7, and 9 with N going from 2K - 3 up to 250. Table 2 shows that both absolute and relative differences uniformly decrease as *K* increases.

4.3. Estimation of the IC FAR for M=1. The FAR approximation from (14) is also valid for M=1. Using the FAR approximation for M=1 and repeating the same arguments for the M=0 case, it can be shown that the FAR at M=1 can be approximated as

$$P_{\text{FA}}(1) \approx P(\hat{\lambda}_2 > \Lambda_2 \mid 1),$$
 (21)

where Λ_2 is the solution to the equation $1 + \ln(\hat{\lambda}_2) - \hat{\lambda}_2 + 2\gamma_{\rm IC}(K-1)/N = 0$. The solution for Λ_2 can be found numerically with the same method used for Λ_1 with the M=0 case.

The difference between the analysis of the M=0 and M=1 cases lies in the way we determine the probability of the events on the right-hand sides of (18) and (21). The probability of the event $\hat{\lambda}_1 > \Lambda_1$ can be estimated using the TW distribution. However, the TW law is not applicable to estimating the probability of the event $\hat{\lambda}_2 > \Lambda_2$ because it applies to the largest, not the second largest eigenvalue.

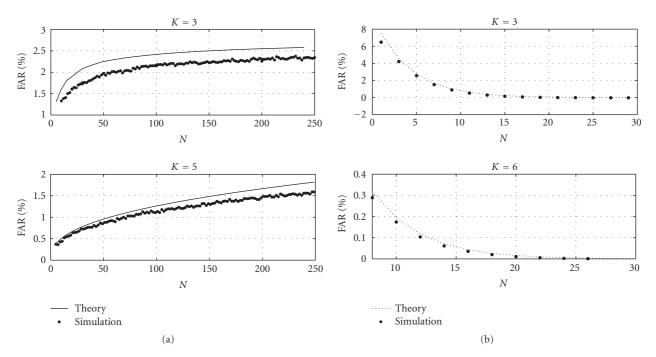


FIGURE 4: (a) (plates on left) AIC FAR for different array sizes as a function of sample size with no sources present. (b) (plates on right) MDL FAR for different array sizes as a function of sample size with no sources present.

A hypothesis test for the presence of M sources, however, can be constructed using the TW distribution based on the following theorem (whose proof is given in [16, pages 303 and 321]).

Eigenvalue Inclusion Principle. Let $\lambda_{M,K}^{[M+1]}$ denote the (M+1)th largest sample eigenvalue of a $K \times K$ covariance matrix constructed from the output signal from a K element array containing M sources (where M < K and the sources are as described earlier) along with noise $\sim \mathcal{N}_C(0,1)$. Let $\lambda_{0,K-M}^{[1]}$ denote the largest eigenvalue of a $(K-M)\times (K-M)$ covariance matrix constructed from the output signal from a K-M element array containing zero sources and only noise $\sim \mathcal{N}_C(0,1)$. Then it follows that:

$$P\left(\lambda_{M,K}^{[M+1]} \ge x\right) \le P\left(\lambda_{0,K-M}^{[1]} \ge x\right) \quad \forall x \in \mathbb{R}.$$
 (22)

This theorem essentially relates the CDF for the largest noise eigenvalue from a K element array having M sources with the CDF for the largest eigenvalue from a "noise" covariance matrix for a (K-M) element array. For the case of M=1, the eigenvalue inclusion theorem and (21) imply an upper bound on the FAR for M=1 that can be expressed in terms of the largest eigenvalue of a noise covariance matrix:

$$\begin{split} &P_{\text{FA}}(1) \approx P\left(\hat{\lambda}_{2} > \Lambda_{2} \mid 1\right), \\ &P\left(\lambda_{1,K}^{[2]} \geq x\right) \leq P\left(\lambda_{0,K-1}^{[1]} \geq x\right) \\ &\Longrightarrow P_{\text{FA}}(1) \leq P\left(\lambda_{0,K-1}^{[1]} > \Lambda_{2}\right). \end{split} \tag{23}$$

The probability of the event on the right-hand side of (23) now can be estimated using the TW law, since it involves the largest eigenvalue of a covariance matrix containing no sources. Proceeding as before with the M=0 case, this upper bound can be expressed in terms of the TW CDF as

$$P_{\text{FA}}(1) \le 1 - P\left(F_2 \left\lceil \frac{\Lambda_2 - \mu_{K-1,N}}{\sigma_{K-1,N}} \right\rceil \right).$$
 (24)

Our analysis supports the conjecture that a single source will "pull up" the largest noise eigenvalue as the source's power increases [16]. Figure 5 shows the simulated FARs for the AIC (top panel) and MDL (lower panel) for an input from a 3-element ULA containing a single source. The FARs are computed as a function of the sample size, where for each N, estimates are obtained from 10^5 Monte-Carlo simulations. The simulations were run at different signal to noise ratios (SNR) for the source. Figure 5 shows that as the SNR increases, the FAR also increases and approaches an upper limit. From (21), this implies that as the SNR increases, the distribution for the second largest eigenvalue shifts to larger values. From (22), we know the second largest eigenvalue's distribution is bounded above as the source power becomes asymptotically large.

Figure 6 compares the upper bound for the FAR obtained using the TW distribution from (24) with the estimated FAR upper bound obtained from simulations using a source with SNR = 40 dB. The top panel shows the FAR upper bounds for the AIC when K = 3 and 9. For K = 3, the upper bound derived from the TW distribution is much larger than the simulation estimated FAR upper bound. This is attributable to two factors. First, (24) shows that the eigenvalue inclusion

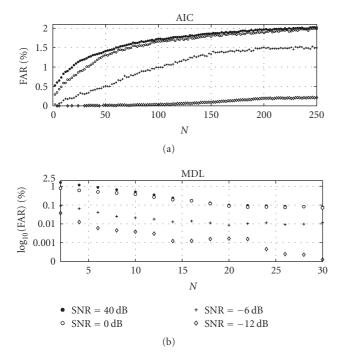


FIGURE 5: Estimated FARs for a single source from a 3-element ULA as a function of the number of samples.

principle overestimates the true FAR since it replaces the probability of the event of interest $(\lambda_{1,K}^{[2]} \geq \Lambda_2)$, with an event $(\lambda_{0,K-1}^{[1]} \geq \Lambda_2)$, whose probability is larger. Second, Observation 2 shows that the use of the TW law in evaluating the probability of the event $(\lambda_{0,K-1}^{[1]} \ge \Lambda_2)$ gives a probability slightly larger than the true probability. The bottom panel in Figure 6 compares the estimated upper bound for the FAR with that obtained using the eigenvalue inclusion principle and the TW distribution for the MDL. The FARs for the MDL are compared for two different array sizes of K = 3and K = 6. Similar to the AIC, the MDL results also show that the agreement between the TW and the true largest noise sample eigenvalue improves as K increases, as expected from Observation 3. For K = 6, in fact, the two estimated and TW derived FARs are seen to be practically identical. This is again consistent with Observation 4, which suggests that the agreement of the TW and largest noise eigenvalue CDFs improves for events lying further out in the distribution's right-tail.

The results from Figure 6 raise the question of which one of the two overestimation factors is the dominant one. If the eigenvalue inclusion theorem produced a very tight upper bound and the majority of the overestimation was due to TW distribution approximation, then this would suggest a possible means of improving the upper bounds through the use of correction factors to the approximate distribution function. To obtain an understanding of the relative importance of the two overestimation factors, Figure 7 replotted the FARs for the AIC in Figure 6 for K=3. Additionally, Figure 7 also plotted the FAR derived from the eigenvalue inclusion principle using (23). The FAR obtained using the eigenvalue

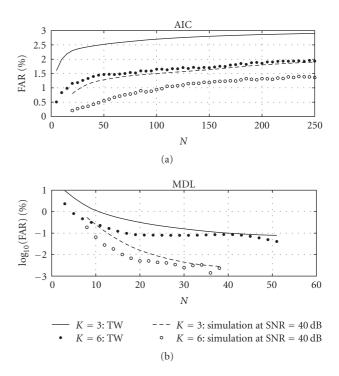


FIGURE 6: Comparison of TW FAR Upper Bound with Estimated FAR Upper Bound.

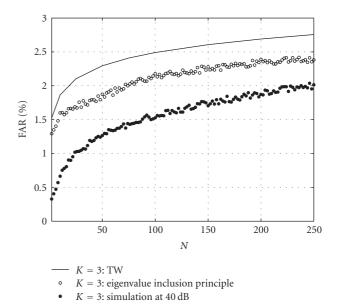


FIGURE 7: Contributions to the Overestimation in the FAR of the AIC.

inclusion principle, shown as the open circles, is about 0.5% above the simulated FAR upper bound. The TW approximation of the eigenvalue inclusion principle condition leads to a further overestimation of about an additional 0.5%, as indicated by the solid line. In this particular example, the contributions from the eigenvalue inclusion principle and the TW approximation are comparable.

5. Conclusions

Information-theoretic methods for model selection are perhaps the most commonly used means for source enumeration in signal processing. The implementation of these methods, however, requires the use of large sample approximations, thereby calling into question the performance of these methods for small sample sizes [1, 5]. As discussed in the introduction, past performance analyses either have relied on the use of large sample size assumptions, and large array sizes, or are computationally complicated and expensive to use. In this paper, we presented a simple, computationally efficient method for FAR estimation using a recent development from random matrix theory known as the Tracy-Widom (TW) law.

The TW law was introduced as a simple means of approximating the distribution for the largest eigenvalue of a covariance matrix from the output signal of an array containing only white noise. It was shown that the TW law allows the largest sample eigenvalue to be expressed in a standardized form whose distribution is independent of the sample size or array size. For a wide range of array and sample sizes, it was shown that the TW distribution approximates the right-hand tail of the true distribution for the largest sample eigenvalue to within 1%. These results set the TW distribution apart from other distributions used for the largest noise eigenvalue, which are either based on large sample sizes [17], require the use of lookup tables that are functions of both K and N [18], or are numerically difficult to evaluate [19].

We analyzed the performance of the AIC and MDL for small sample sizes under the condition that the noise variance is known. A general information criterion applicable to both the MDL and AIC was derived under this condition. Using the approximation that the FAR for M sources can be estimated as the probability of the single event that the IC estimates M + 1 sources present, we derived the criteria for FAR when M = 0 and when M = 1 in terms of the sample eigenvalues. It was shown that the FAR for M = 0 could be approximated as the probability that the largest noise eigenvalue exceeded a critical value. The critical value was the zero of a nonlinear equation having one real root, and its value could easily be obtained numerically. In this case, the FAR could be directly estimated using the TW distribution. Because the TW predicted FARs were always overestimates of the true FAR, the FARs obtained using the TW distribution will be conservative estimates of the true FAR. Our computation and simulation results demonstrate that the agreement between the estimated FAR using the TW distribution and with the simulated FARs improved uniformly with increasing K. The TW approximated FAR and the FAR estimated by simulation showed better agreement with the MDL than for the AIC. This was due in part to the fact that the FARs for the MDL were smaller than the AIC and could therefore be better approximated using the TW distribution.

For the case where there is one external source in the receiver input (M = 1), an estimate for the FAR was derived based on the eigenvalue inclusion principle. It was shown

that the eigenvalue inclusion principle and the use of the TW distribution both contribute to the overestimation in the FAR. Thus, FAR estimates obtained with the TW distribution when sources are present will always be upper bounds for the true FAR. Similar to the FAR for the M=0 case, it was shown that this upper bound becomes uniformly tighter as the array size increases. For the AIC, for example, it was shown that as the array size increased from K=3 to K=9, the relative difference between the true and upper bound FAR uniformly decreased from 20% to 10%.

Recent developments in random matrix theory should allow for further improvements in the FAR estimates using the TW law and also the possibility that the TW law can be used to estimate missed detection probabilities. Recent analyses have shown that the TW law can be generalized to non-central white Wishart distributions using a standardized test statistic similar to that used in the TW distribution for white Wishart distributions [29, 30]. There is evidence based on empirical studies in the engineering literature [12] that support the notion that such an approach is possible. These results, while still preliminary, would allow the TW law to be extended so that it could be directly applied to signal eigenvalues and not just noise eigenvalues, thereby making the use of the eigenvalue inclusion principle unnecessary. Since the use of eigenvalue inclusion principle artificially inflates the FAR estimates obtained, this approach would produce tighter bounds for the FAR and also allow for more precise statistical analyses.

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